

The excitation of the Earth's polar motion

SEMINAR **II**

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鍾霽詠

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- Wilson, C., 1985. Discrete Polar Motion Equations, *Geophysical Journal Royal Astronomical Society*, 80, 551-554.

References

Earth's Rotation

Astronomical (external torques → angular momentum change)

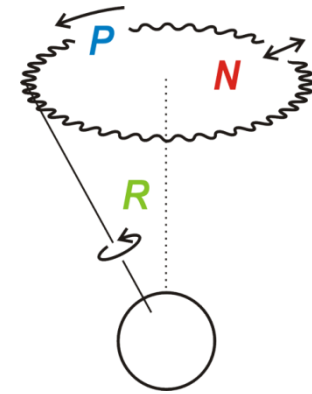
Precession **P**

Nutations **N**

Librations

Tidal Braking

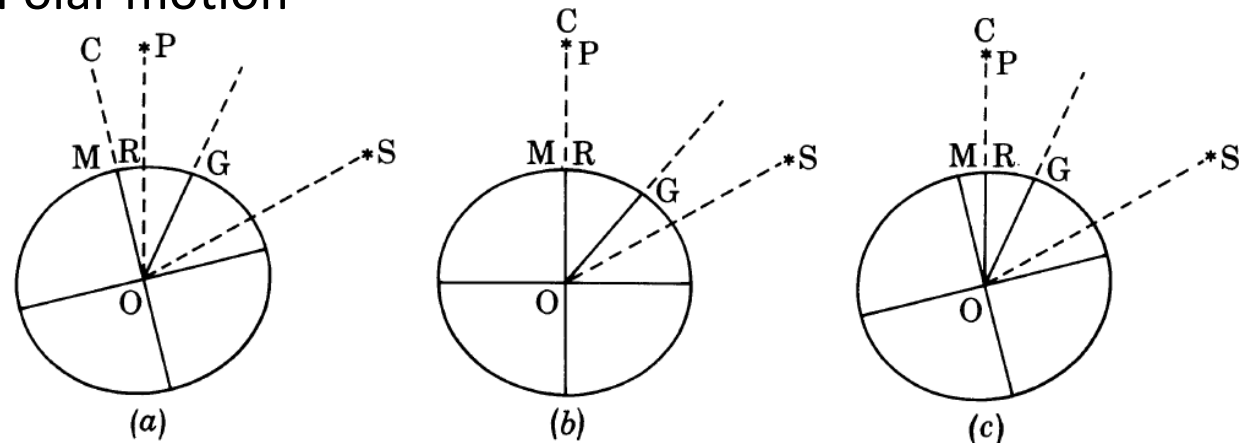
Milankovitz Cycles



Geophysical (internal forces → no angular momentum change)

Length-of-day (LOD) change

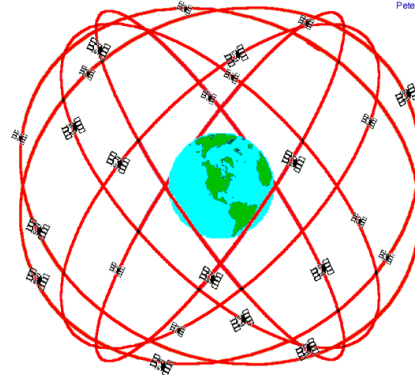
Polar motion



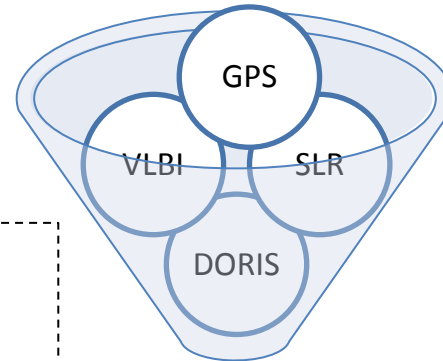
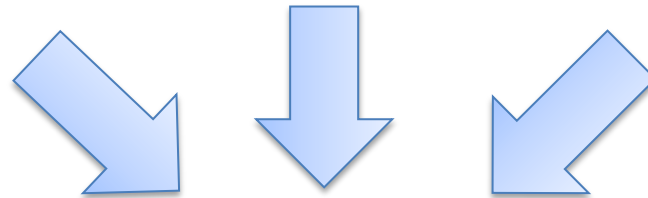
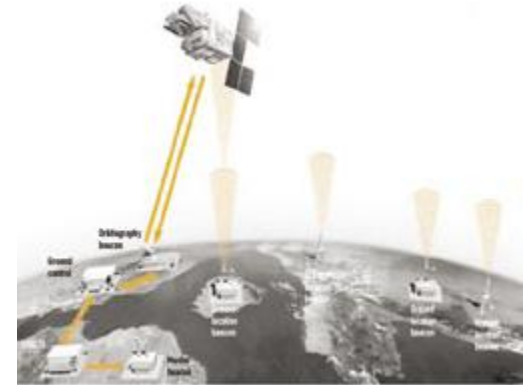
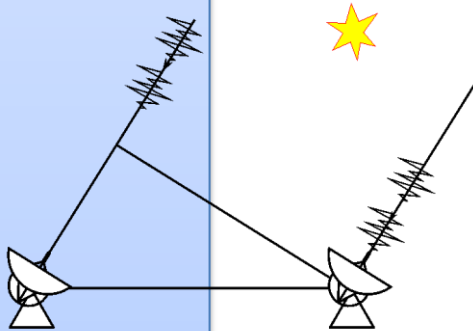
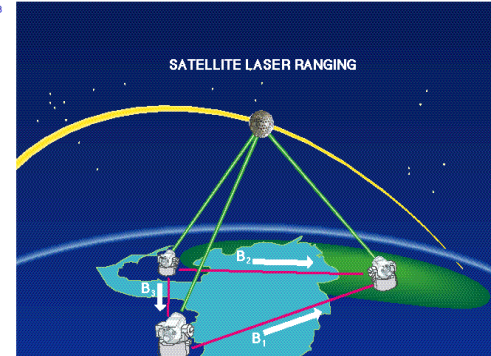
P, Polaris; **S**, star; **M**, geographical (body-fixed) pole; **G**, observatory; **O**, centre of the Earth; **R**, rotation pole; **C**, North Celestial Pole

Earth's Rotation

Nowadays, four main geodetic techniques are used to compute accurate coordinates: the **GPS, VLBI, SLR, and DORIS**.



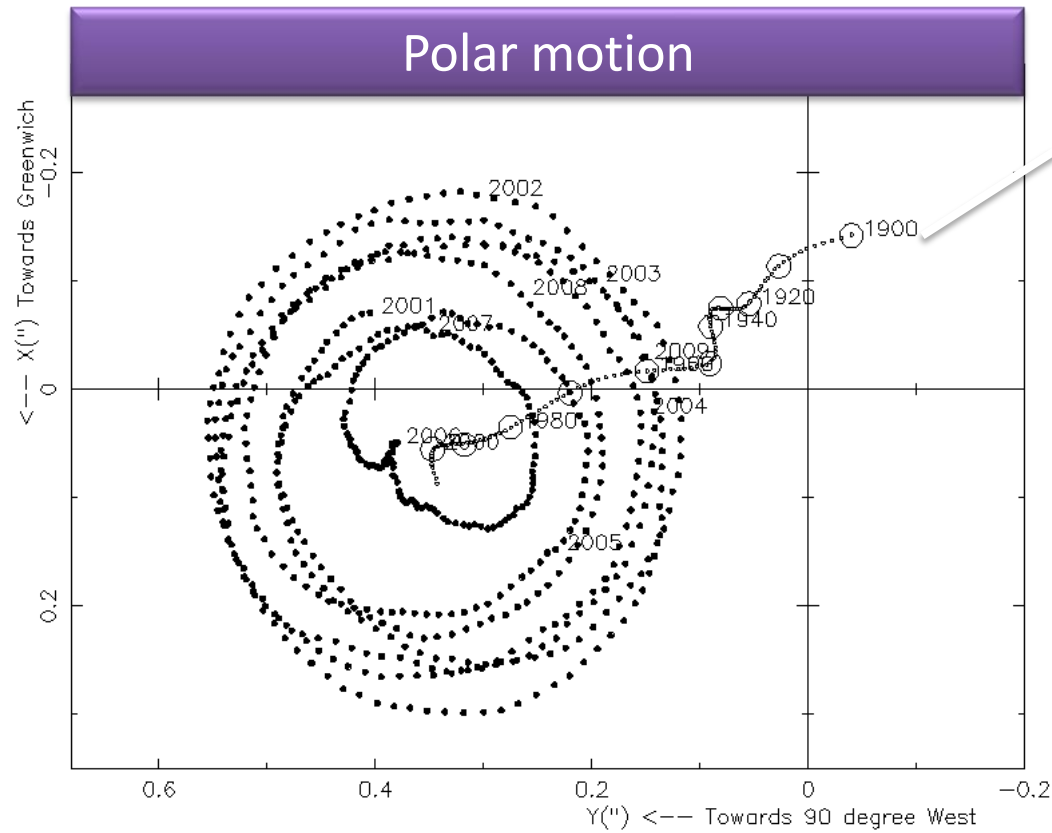
Peter H. Dana 9/22/98



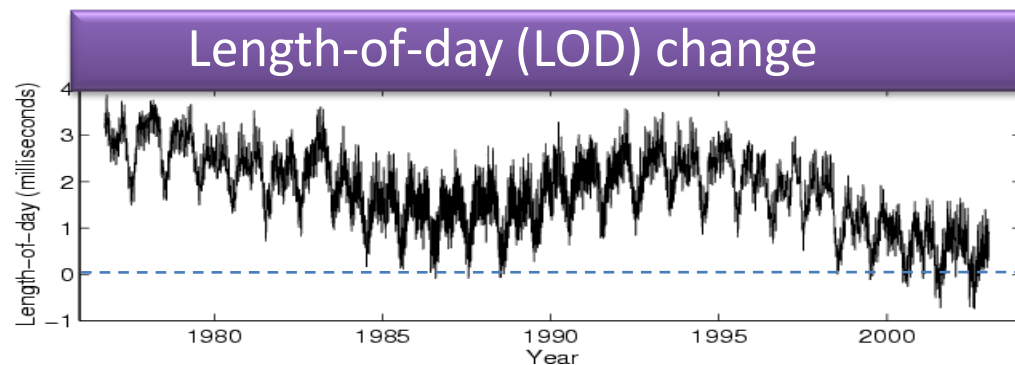
↓
ICRF-ITRF 

- | | |
|-------|---|
| SLR | Satellite Laser Ranging |
| VLBI | Very-Long-Baseline Interferometry |
| GPS | Global Positioning System |
| DORIS | Doppler Orbitography and Radiopositioning Integrated by Satellite |
| ITRF | International Terrestrial Reference Frame |
| ICRF | International Celestial Reference Frame |

Earth's Rotation



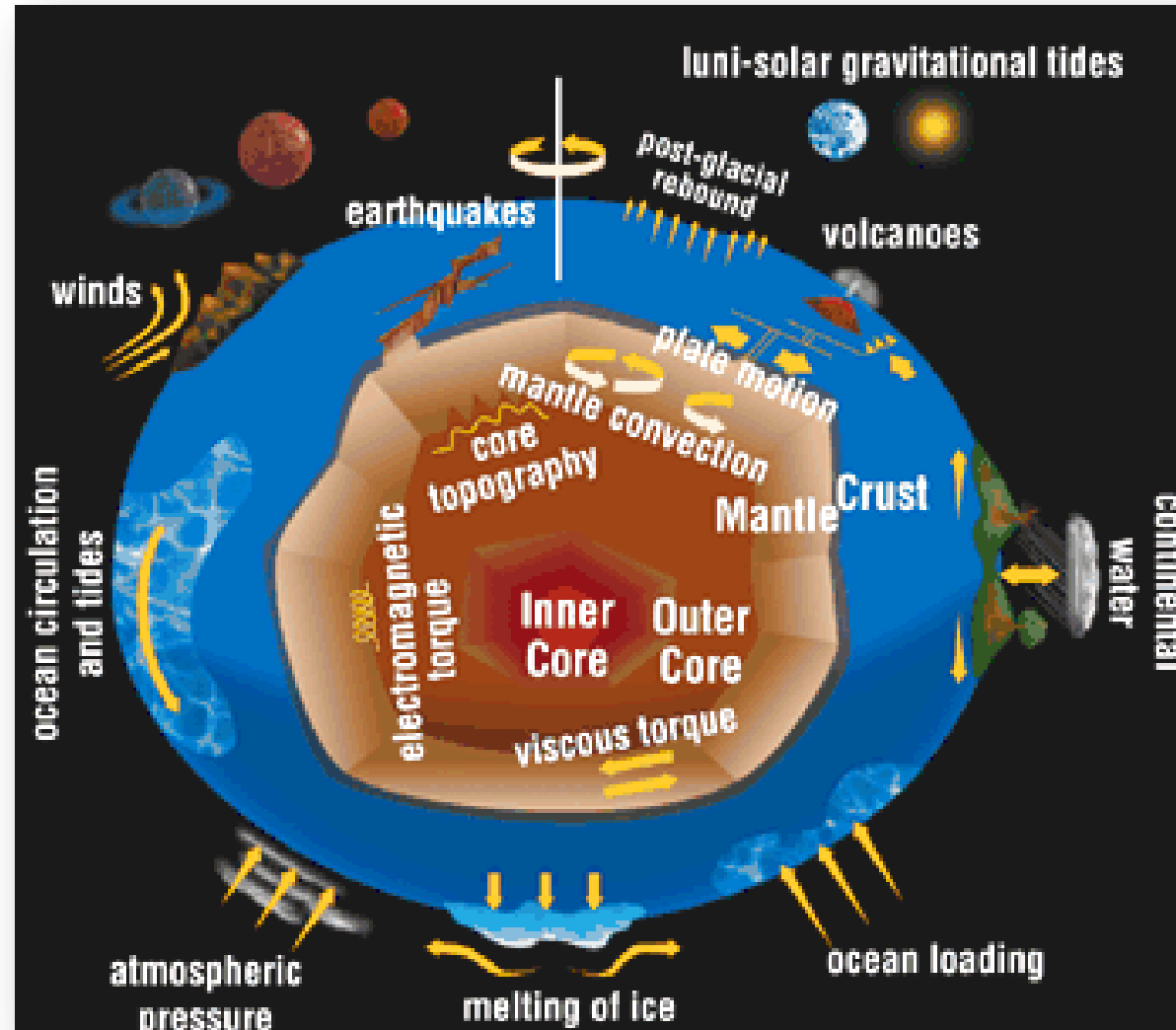
North Pole



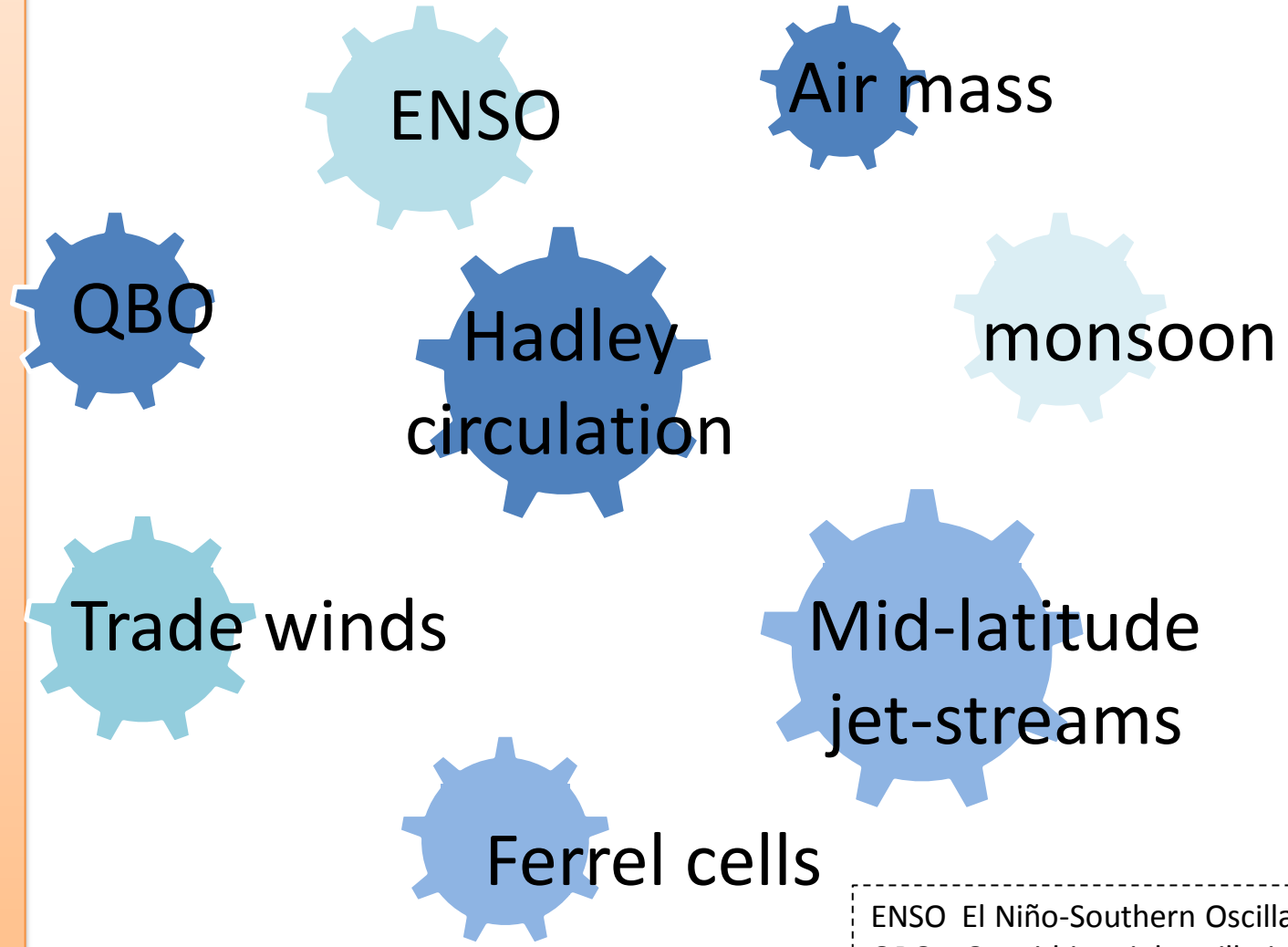
86400 seconds

Earth's Rotation

Earth system



What's in the atmosphere?



ENSO El Niño-Southern Oscillation
QBO Quasi-biennial oscillation

How is their coupling ?

All components of angular momentum would be zero if that surface were **perfectly spherical** and **perfectly slippery**, for then normal stresses would exert no couple and tangential (frictional) stresses would be absent. In practice both 'topographic' and **frictional stresses** are present, with **normal pressure forces** acting on the Earth's equatorial bulge playing a major role in the coupling associated with the changes in excitation that manifest themselves in the observed polar motion.

A brief summary

Meteo- rological

Atmospheric excitation

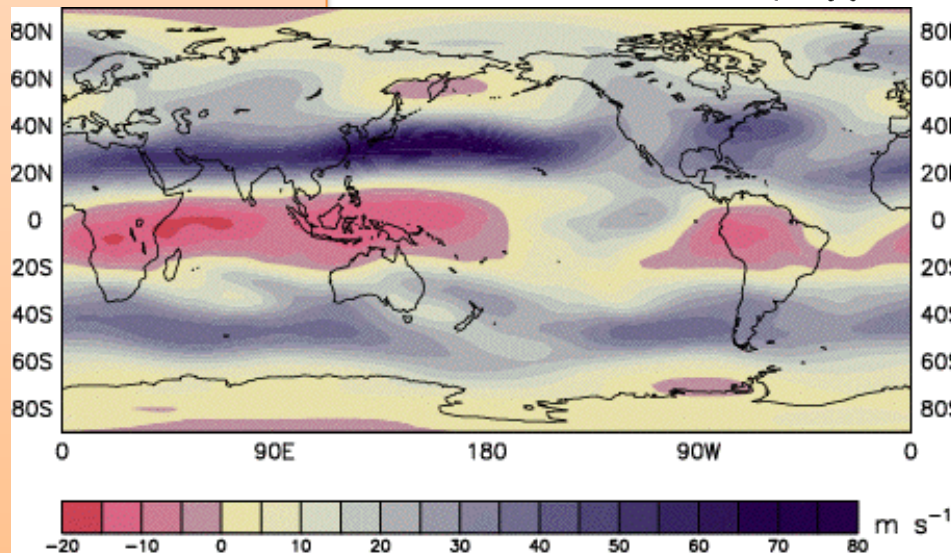
$$\chi_1 = \chi_1^P + \chi_1^W = \frac{-1.00\bar{R}^4}{(C-A)g} \iint p_s \sin \phi \cos^2 \phi \cos \lambda \, d\lambda \, d\phi$$

$$- \frac{1.43\bar{R}^3}{\Omega(C-A)g} \iiint (u \sin \phi \cos \phi \cos \lambda - v \cos \phi \sin \lambda) \, d\lambda \, d\phi \, dp,$$

$$\chi_2 = \chi_2^P + \chi_2^W = \frac{-1.00\bar{R}^4}{(C-A)g} \iint p_s \sin \phi \cos^2 \phi \sin \lambda \, d\lambda \, d\phi$$

$$- \frac{1.43\bar{R}^3}{\Omega(C-A)g} \iiint (u \sin \phi \cos \phi \sin \lambda + v \cos \phi \cos \lambda) \, d\lambda \, d\phi \, dp,$$

$$\chi_3 = \chi_3^P + \chi_3^W = \frac{0.70\bar{R}^4}{Cg} \iint p_s \cos^3 \phi \, d\lambda \, d\phi + \frac{\bar{R}^3}{C\Omega g} \iiint u \cos^2 \phi \, d\lambda \, d\phi \, dp.$$



Zonal wind field near jet stream levels (sampled here for January 1997), the primary contributor to atmospheric angular momentum and length of day changes.

- (u, v, w) Eulerian flow velocity vector
- P_s surface pressure
- A, C principal moments of inertia of a spheroid
- R mean radius of the Earth
- Ω mean angular velocity of the Earth
- (λ, ϕ, r) spherical polar coordinates

Dynamics of the earth's rotation

1

$$dH_i/dt + \epsilon_{ijk} \omega_j H_k = L_i, \quad \text{※ Euler's dynamical equations}$$

$$H_i(t) = I_{ij}(t) \omega_j(t) + h_i(t).$$

$$I_{ij} \equiv \int_V \rho (x_k x_k \delta_{ij} - x_i x_j) dV$$

$$h_i \equiv \int_V \rho \epsilon_{ijk} x_j u_k dV$$

2

$$d(I_{ij} \omega_j + h_i)/dt + \epsilon_{ijk} \omega_j (I_{kl} \omega_l + h_k) = L_i.$$

$$I_{ij}(t) = \begin{pmatrix} A & 0 & 0 \\ 0 & A & 0 \\ 0 & 0 & C \end{pmatrix} + \Delta I_{ij}(t).$$

$$(\omega_1, \omega_2, \omega_3) = (m_1, m_2, 1 + m_3) \Omega,$$

※ ignoring products of small quantities

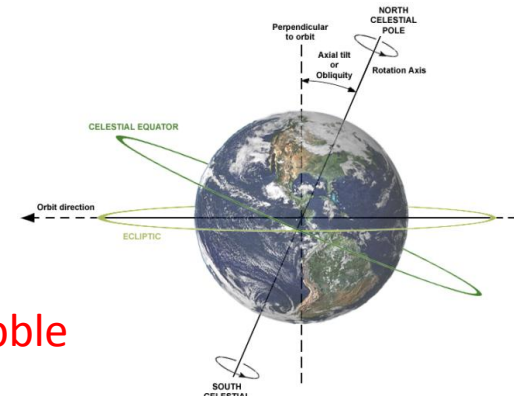
ω angular velocity
 L_i externally applied torque
 H_i absolute angular momentum
 ϵ_{ijk} 'alternating' tensor
 x_i body-fixed axes
 I_{ij} (variable) inertia tensor
 ρ density
 δ_{ij} Kronecker delta
 h_i angular momentum
 (u,v,w) Eulerian flow velocity vector
 A,C principal moments of inertia of a spheroid
 m_i direction cosines of rotation axis
 Ω mean angular velocity of the Earth

$$|\Delta I_{ij}| \ll C, \quad |h_i| \ll \Omega C, \quad |m_i| = O(10^{-7}), \quad \dot{m}_i \ll \Omega$$

3

$$\left. \begin{aligned} \dot{m}_1/\sigma_r + m_2 &= \psi_2, \\ \dot{m}_2/\sigma_r - m_1 &= -\psi_1, \\ \dot{m}_3 &= \psi_3. \end{aligned} \right\}$$

$$\sigma_r \equiv (C - A) \Omega / A \quad \times \text{ Chandler wobble}$$



$$\left. \begin{aligned} \psi_1 &= (\Omega^2 \Delta I_{13} + \Omega \Delta \dot{I}_{23} + \Omega h_1 + \dot{h}_2 - L_2) / \Omega^2 (C - A), \\ \psi_2 &= (\Omega^2 \Delta I_{23} - \Omega \Delta \dot{I}_{13} + \Omega h_2 - \dot{h}_1 + L_1) / \Omega^2 (C - A), \\ \psi_3 &= \left(-\Omega^2 \Delta I_{33} - \Omega h_3 + \Omega \int_0^t L_3 dt' \right) / \Omega^2 C, \end{aligned} \right\}$$

4

$$\left[\begin{aligned} \mathbf{m}(t) &= e^{i\lambda_r t} \left((\mathbf{m}_0) - i\sigma_r \int_0^t \boldsymbol{\psi}(\tau) e^{-i\sigma_r \tau} d\tau \right) \\ m_3 &= \psi_3 + \text{constant}, \end{aligned} \right.$$

σ_r rigid-body free wobble frequency
 $\boldsymbol{\psi}$ non-homogeneous forcing terms

$$\Delta \mathbf{I} \equiv \Delta I_{13} + i\Delta I_{23}$$

$$\mathbf{h} \equiv h_1 + ih_2$$

$$\mathbf{L} \equiv L_1 + iL_2.$$

$$\left[\begin{aligned} \mathbf{m} &\equiv m_1 + im_2, \\ \boldsymbol{\psi} &\equiv \psi_1 + i\psi_2 = [\Omega^2 \Delta \mathbf{I} - i\Omega \Delta \dot{\mathbf{I}} + \Omega \mathbf{h} - i\dot{\mathbf{h}} + i\mathbf{L}] / \Omega^2 (C - A) \end{aligned} \right.$$

$$\Omega C(1 + m_3) + \Omega \Delta I_{33} + h_3 = \text{constant.}$$

✧ absence of external torques ($L_i = 0$)

$$m_3 = (\omega_3 - \Omega) / \Omega$$

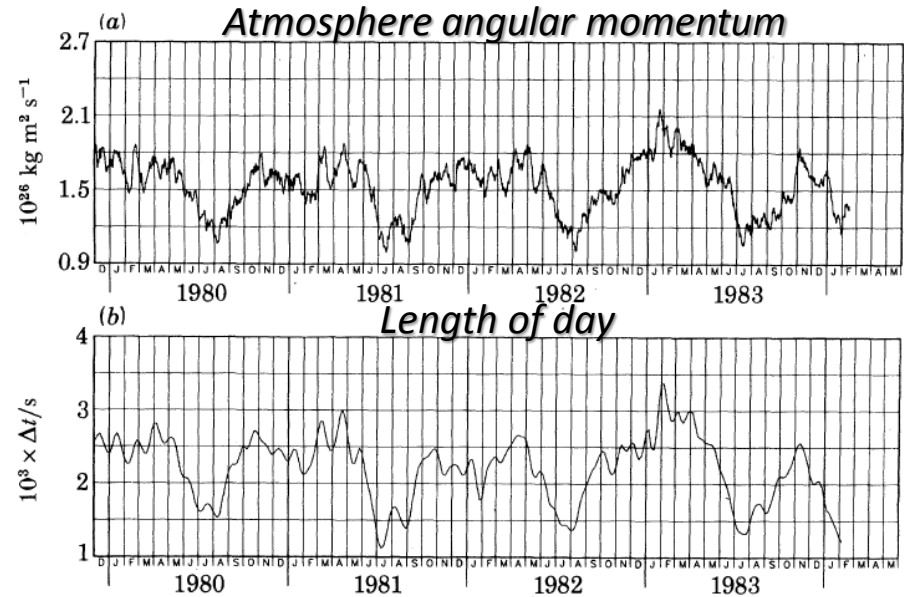
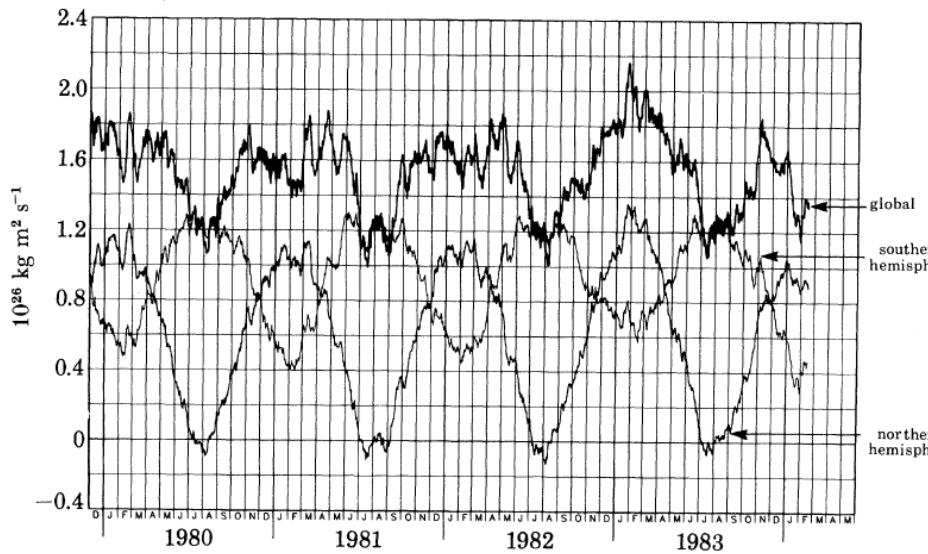
$$\Lambda = 2\pi / \omega_3 \quad \Lambda_0 = 2\pi / \Omega.$$

$$m_3 = -\Delta\Lambda / \Lambda_0$$

$\Delta\Lambda$ difference of length-of-day from its mean value

Atmosphere angular momentum

1 December 1979--15 February 1984



✧ European Centre for Medium-Range Weather Forecasts (E.C.M.W.F.)

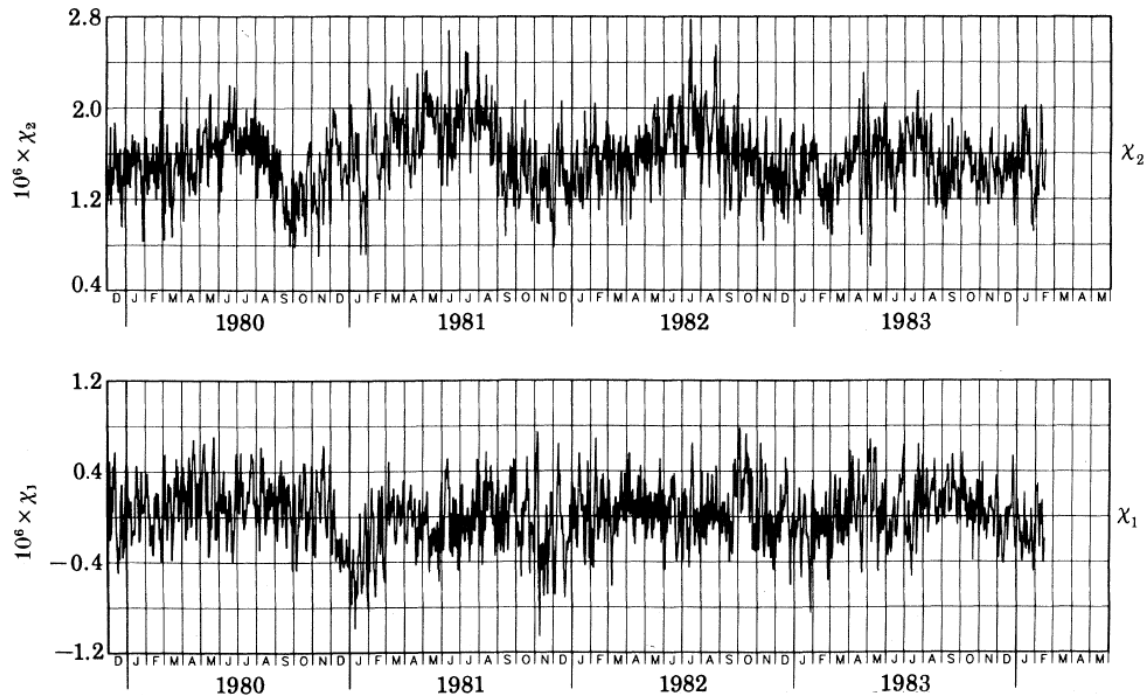
✧ Bureau International de l'Heure (B.I.H.)

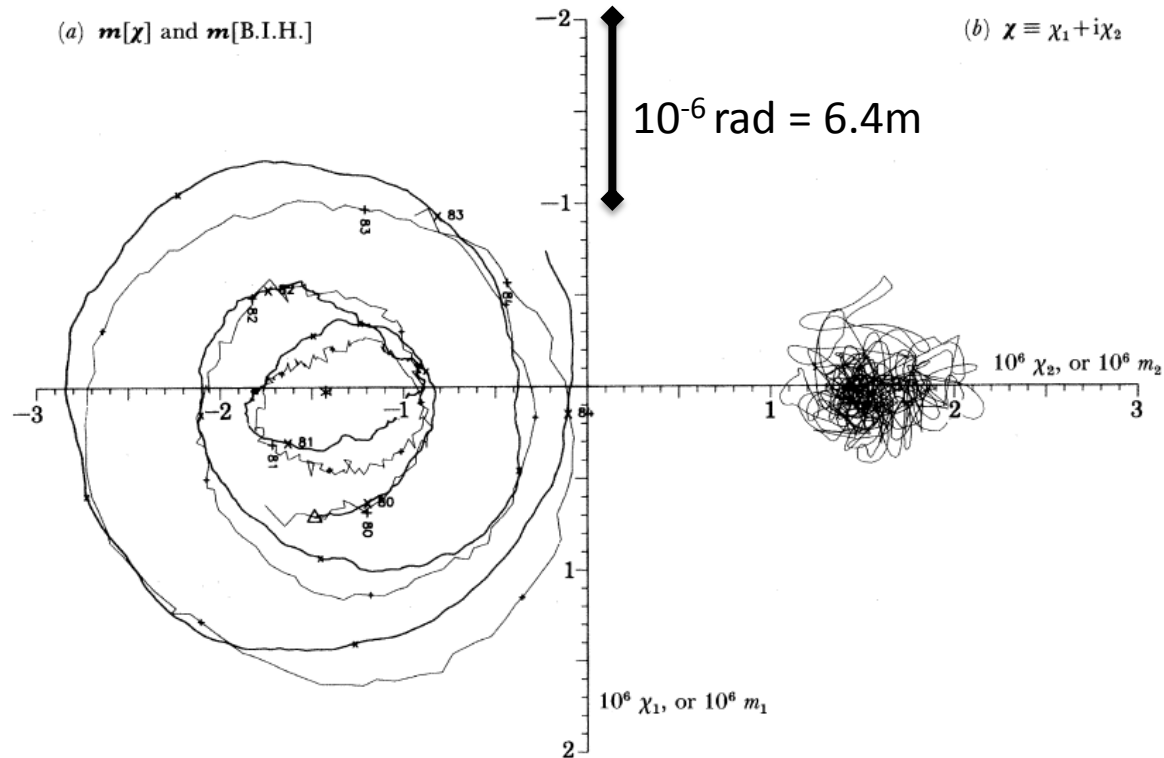
$\tilde{\chi}$ dimensionless atmospheric
'effective angular momentum'

$$\tilde{\chi} \equiv \tilde{\chi}_1 + i\tilde{\chi}_2 = (\Omega\Delta\mathbf{I} + \mathbf{h})/\Omega(C - A)$$

$$m(t) = e^{i\sigma_r t} \left[m(0) - i\sigma_r(1 + \sigma_r/\Omega) \int_0^t \tilde{\chi}(\tau) e^{-i\sigma_r \tau} d\tau \right] - (\sigma_r/\Omega) [\tilde{\chi}(t) - e^{i\sigma_r t} \tilde{\chi}(0)].$$

Atmosphere angular momentum
1 December 1979--15 February 1984



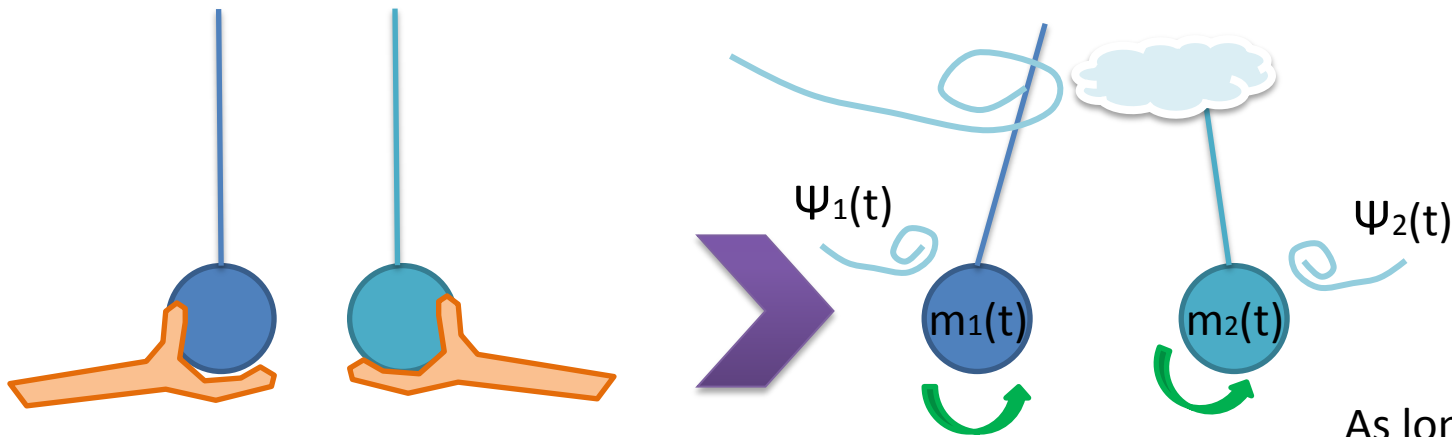


Our evaluation of the atmospheric equatorial effective angular momentum functions from meteorological data over an interval corresponding to 3.6 Chandlerian periods indicates that **atmospheric excitation** alone was sufficient to account for the observed polar motion over that interval. There is apparently **no need to invoke substantial excitation** either by the fluid core of the Earth, or movements in the mantle associated with earthquakes, of which, admittedly, there were no major instances during the interval covered by our study.



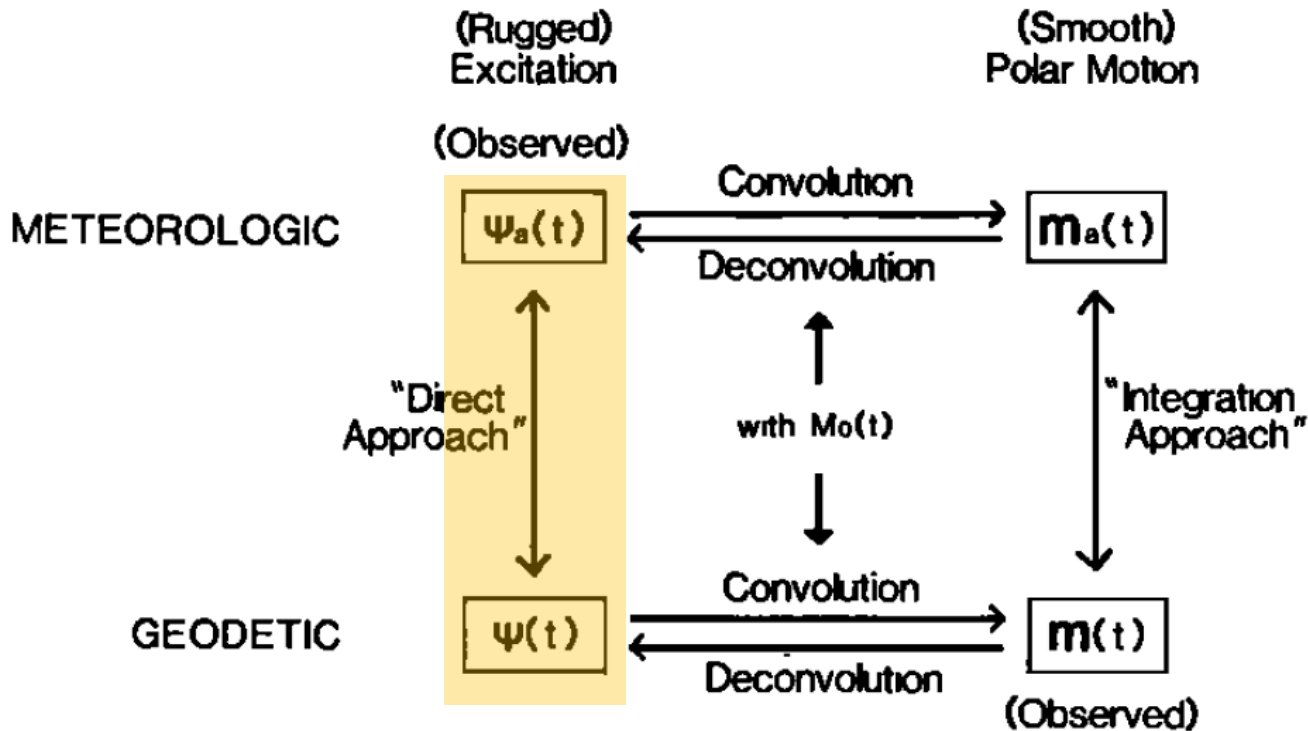
The conclusion
is unjustified !!





$$m(t) = m(0)\exp(i\sigma t) + \psi(t) * m_o(t).$$

As long as the initial conditions are the same, we will always have $m_1(t) \doteq m_2(t)$ regardless of how different $\psi_1(t)$ and $\psi_2(t)$ are.



Hypothetical excitation

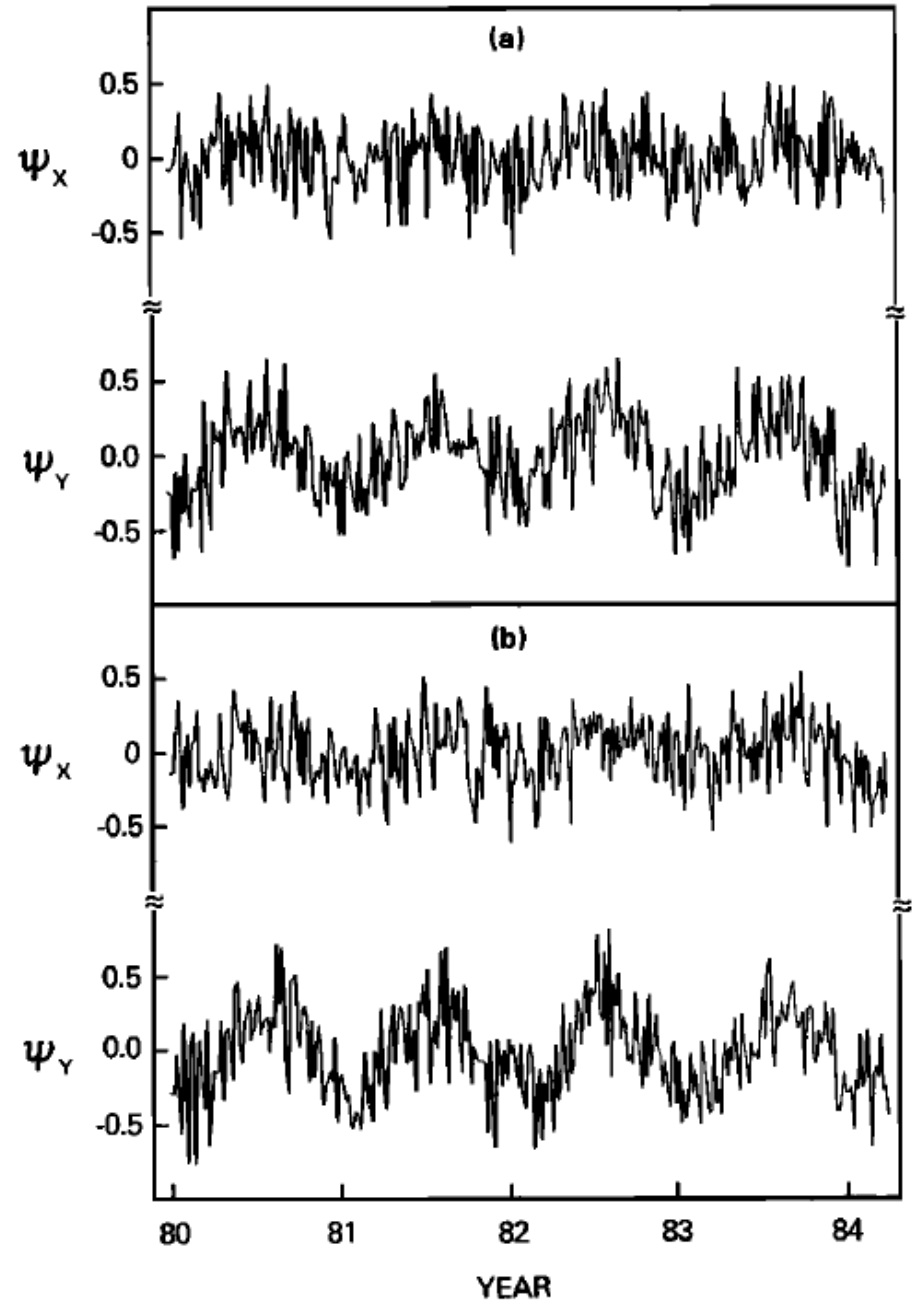
$$\psi_x(t) = A_x \cos(\omega t + \theta_x) + N_x(t),$$

$$\psi_y(t) = A_y \cos(\omega t + \theta_y) + N_y(t).$$

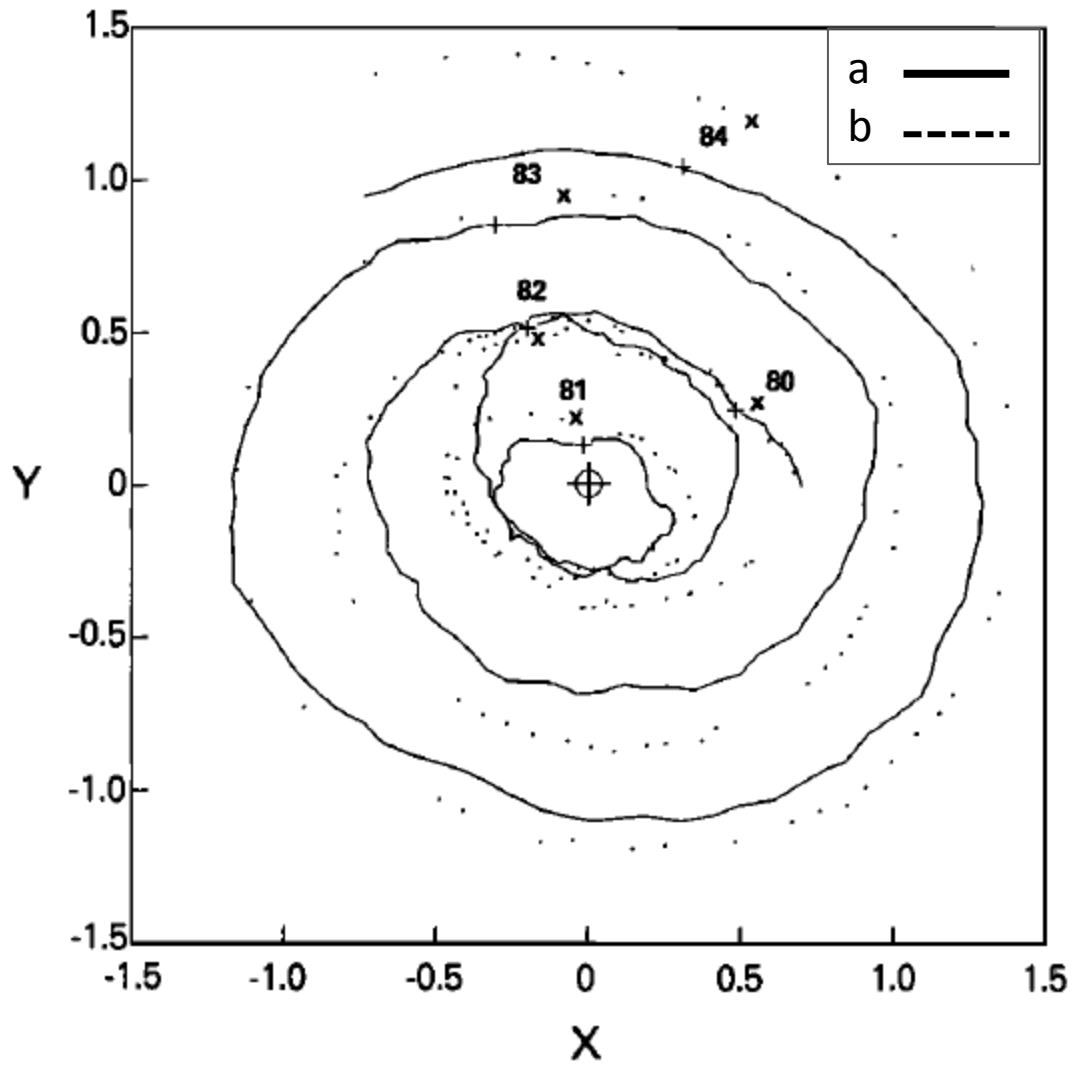
➤ $N_x(t)$ and $N_y(t)$ denote two computer-generated, zero-mean, Gaussian random series with standard deviations S_x and S_y .

➤ $\omega = 2\pi/365$ days

➤ 5-day intervals



$$m(t) = m(0)\exp(i\sigma t) + \psi(t) * m_o(t).$$





$$(1a) \quad X(t) = \frac{i}{\sigma_c} \frac{dM(t)}{dt} + M(t).$$

$$(1b) \quad \frac{\sigma_c}{\sigma_c - 2\pi f}$$

$$(2a) \quad X_t = \frac{i}{\sigma_c T} M_t - \exp(i\sigma_c T) M_{t-T}$$

$$(2b) \quad \frac{-i\sigma_c T}{1 - \exp[i(\sigma_c - 2\pi f)T]}$$

$$(3a) \quad X_t = \frac{i \exp(-i\pi F_c T)}{\sigma_c T} [M_{(t+T/2)} - \exp(i\sigma_c T) M_{(t-T/2)}]$$

$$(3b) \quad \frac{-i\sigma_c T \exp[i\pi(F_c - f)T]}{1 - \exp[i(\sigma_c - 2\pi f)T]}$$

$$\ast \sigma_c = 2\pi F_c (1 + i/2Q_c)$$

F_c Chandler's frequency 0.843 cycle/yr

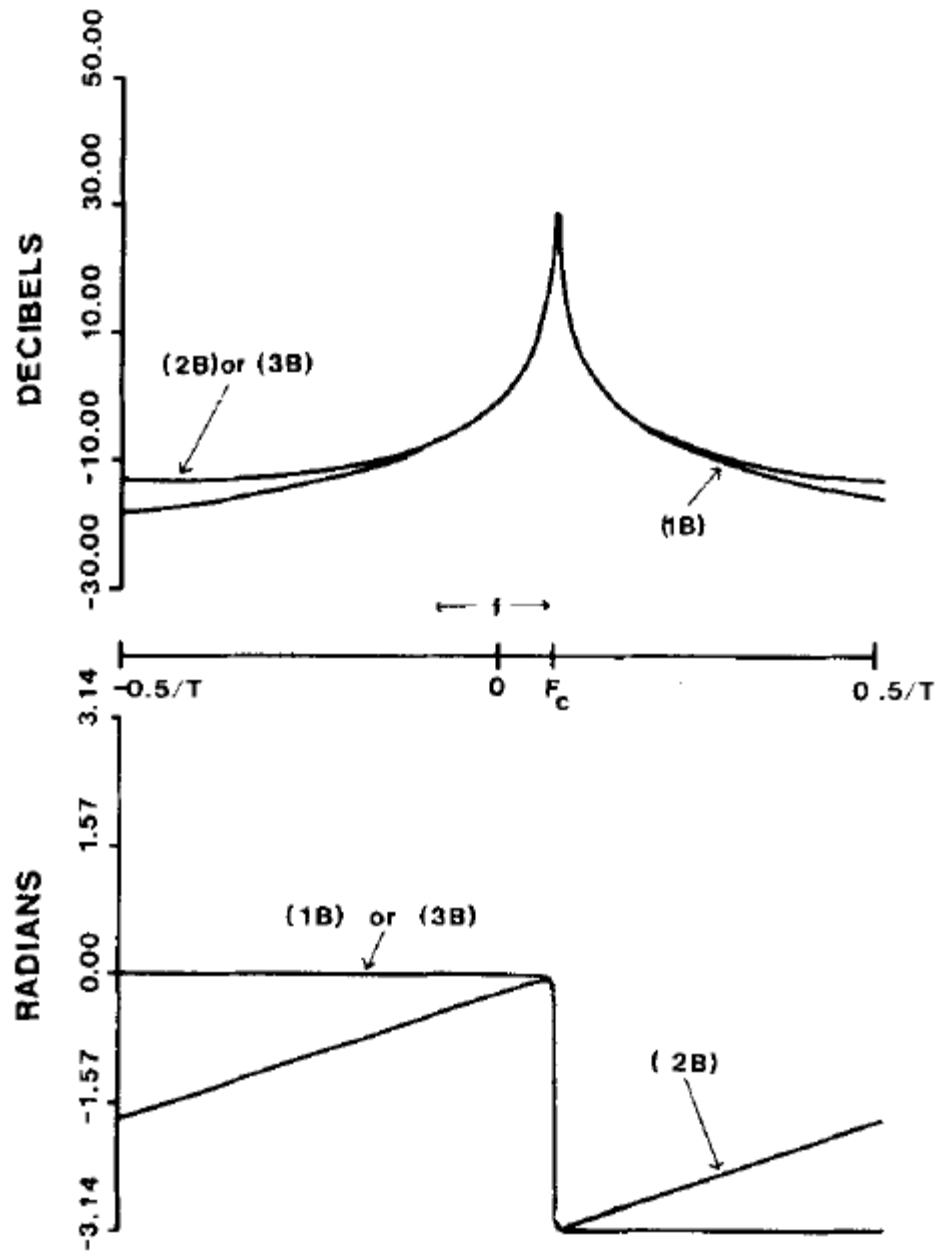
Q_c the dissipation factor 100

$$\ast f = \sigma_c / 2\pi$$

$$Z = \exp(-2\pi ifT)$$

$$\exp(i\sigma_c T)$$

$$\ast \exp[i\pi(F_c - f)T]$$





$$(1a) \quad X(t) = \frac{i}{\sigma_c} \frac{dM(t)}{dt} + M(t).$$

$$(1b) \quad \frac{\sigma_c}{\sigma_c - 2\pi f}$$

$$(2a) \quad X_t = \frac{i}{\sigma_c T} M_t - \exp(i\sigma_c T) M_{t-T}$$

$$(2b) \quad \frac{-i\sigma_c T}{1 - \exp[i(\sigma_c - 2\pi f)T]}$$

$$(3a) \quad X_t = \frac{i \exp(-i\pi F_c T)}{\sigma_c T} [M_{(t+T/2)} - \exp(i\sigma_c T) M_{(t-T/2)}]$$

$$(3b) \quad \frac{-i\sigma_c T \exp[i\pi(F_c - f)T]}{1 - \exp[i(\sigma_c - 2\pi f)T]}$$

$$\ast \sigma_c = 2\pi F_c (1 + i/2Q_c)$$

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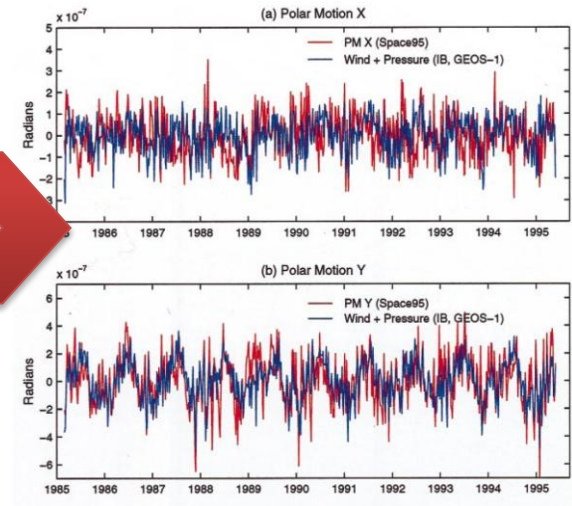
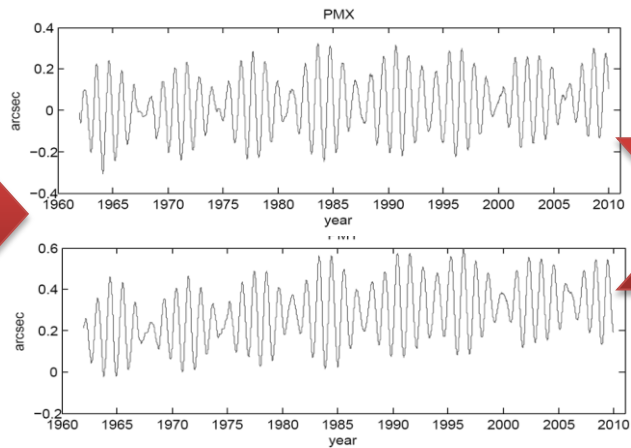
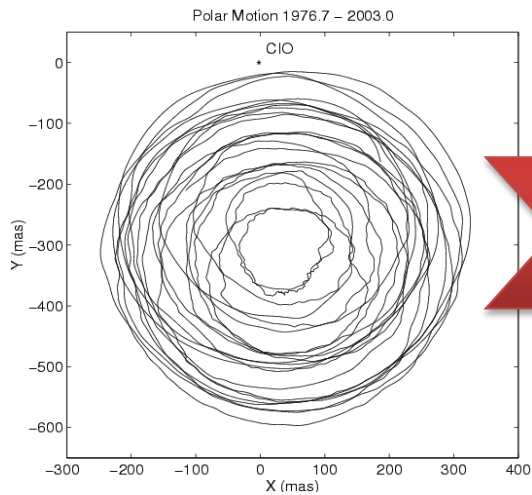
$$(4a) \quad X_t = \frac{i \exp(-i\pi F_c T)}{2\sigma_c T} \llbracket M_{t+T} + [1 - \exp(i\sigma_c T)] M_t - \exp(i\sigma_c T) M_{t-T} \rrbracket$$

$$(4b) \quad \frac{-2i\sigma_c T \exp[i\pi(F_c - 2f)T]}{1 + [1 - \exp(i\sigma_c T)] \exp(-2\pi ifT) - \exp[i(\sigma_c - 4\pi f)T]}$$

$$(5a) \quad M_t = \frac{-i\sigma_c T \exp(i\pi F_c T)}{2} [X_t + X_{t-T}] + \exp(i\sigma_c T) M_{t-T}$$

$$(5b) \quad \frac{-i\sigma_c T \exp(i\pi F_c T) [1 + \exp(-2\pi ifT)]}{2(1 - \exp[i(\sigma_c - 2\pi f)T])}$$

Direct approach !



Conclusions

- Atmospheric angular momentum fluctuations are of interest also to geophysicists and astronomers concerned with the structure and dynamics of the Earth, who must make allowances for the meteorological contribution to the variable rotation of the solid Earth when dealing with effects due to 'non-meteorological' processes.
- If we want to compare a geophysically observed excitation function with the excitation function deduced (via deconvolution) from the polar motion observation, we should do so directly (the "direct approach").

Conclusions

- It would be useful for estimating X_t from M_t since the transfer function would then be the reciprocal of (4b) and thus would attenuate Nyquist frequency variations, a desirable feature if the M_t values are corrupted by noise.
- However, despite decades of effort by many investigators, the major excitation source(s) for the Chandler wobble still remain a mystery.

Thanks for your attention!